Name:	
Instructions:	
• Answer each question to the best of your ability.	
• All answers must be written clearly. Be sure to erase or cross out any work that you do no graded. Partial credit can not be awarded unless there is legible work to assess.	ot want
• If you require extra space for any answer, you may use the back sides of the exam pages. indicate when you have done this so that I do not miss any of your work.	Please
ACADEMIC INTEGRITY AGREEMENT I certify that all work given in this examination is my own and that, to my knowledge, has not be by anyone besides myself to their personal advantage. Further, I assert that this examination was t accordance with the academic integrity policies of the University of Connecticut.	
Signed:(full name)	
(tun name)	

Questions:	1	2	3	4	5	6	Bonus	Total
Points:	20	15	10	10	10	10	10	75
Score:								

Percentage

1. (20 points) Consider the following linear system of equations

$$x_1 - x_2 + 3x_3 = 3$$

$$4x_1 - x_2 + 6x_3 = 9$$

$$2x_1 - x_2 + 4x_3 = 5$$

(a) (5 points) Write a matrix equation and a vector equation which are equivalent to this system.

(b) (5 points) Solve the system of equations and give your solution in parametric vector form.

(c) (5 points) Give the solution of the associated homogeneous equation to this system.

(d) (5 points) Are the vectors $\begin{bmatrix} 1\\4\\2 \end{bmatrix}$, $\begin{bmatrix} -1\\-1\\-1 \end{bmatrix}$, and $\begin{bmatrix} 3\\6\\4 \end{bmatrix}$ linearly independent? If not, give a linear dependence relation among these vectors.

- 2. (15 points) Consider the matrices $A = \begin{bmatrix} 1 & 3 \\ 2 & 5 \end{bmatrix}$, $B = \begin{bmatrix} 1 & -2 & 4 \\ 0 & 3 & -1 \end{bmatrix}$, and $C = \begin{bmatrix} 1 & 0 \\ 2 & -1 \\ 3 & 1 \end{bmatrix}$.
 - (a) (5 points) Circle each expression that is defined.
 - (i) A + B
- (ii) B-C
- (iii) $C + B^T$
- (iv) CA A

- (v) AB
- (vi) BAC
- (vii) CA^T (viii) $(BC)^T$
- (b) (5 points) Compute $C(B + C^T)$.

- (c) (5 points) Find A^{-1} , and use it to solve the three matrix equations
- (i) $A\mathbf{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ (ii) $A\mathbf{x} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ (iii) $A\mathbf{x} = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$.

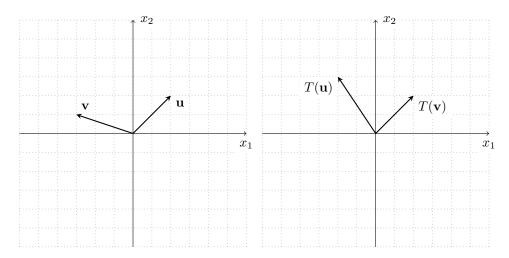
3. (10 points) Consider the linear transformation $T: \mathbb{R}^3 \to \mathbb{R}^2$ defined by

$$T\left(\begin{bmatrix} x_1\\x_2\\x_3\end{bmatrix}\right) = \begin{bmatrix} x_1 - 5x_2 + 4x_3\\x_2 - 6x_3\end{bmatrix}.$$

(a) (5 points) Find the standard matrix of T. That is, find a matrix A such that for all $\mathbf{x} \in \mathbb{R}^3$, we have $T(\mathbf{x}) = \mathbf{A}\mathbf{x}$.

(b) (5 points) Is T one-to-one? Is T onto?

4. (10 points) Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be a linear transformation. Consider the vectors \mathbf{u}, \mathbf{v} in \mathbb{R}^2 given below and to the right. Their images $T(\mathbf{u})$ and $T(\mathbf{v})$ are given below and to the left.



- (a) (5 points) In the left plot, carefully sketch and label the vectors $2\mathbf{u}$, $-2\mathbf{v}$ and $\mathbf{v} \mathbf{u}$.
- (b) (5 points) In the right plot, carefully sketch and label the vectors $T(2\mathbf{u})$, $T(-2\mathbf{v})$ and $T(\mathbf{v} \mathbf{u})$.
- 5. (10 points) Let H be an $n \times n$ matrix and $\mathbf{x} \in \mathbb{R}^{\mathbf{n}}$. Suppose for a fixed \mathbf{c} in \mathbb{R}^n the equation $H\mathbf{x} = \mathbf{c}$ is inconsistent.
 - (a) (5 points) Is H invertible? Justify your answer.

(b) (5 points) Does the homogeneous question $H\mathbf{x} = \mathbf{0}$ have a nontrivial solution? Justify your answer.

,					false by circling True or False appropriately. y have the same number of rows.
,	, ,		·	True	False
(b)	(2 points) many solu		consistent and	has free v	variables then the solution set contains infinitely False
(c)	(2 points)	The equation	$A\mathbf{x} = \mathbf{b}$ is hom	ogeneous i	If the zero vector is a solution. False
(d)	(2 points) trivial solu		of a matrix A	are linear True	ly independent if the equation $A\mathbf{x} = 0$ has the False
(e)	, - ,		an augmented i	[0 0 0	7 0]
				True	False

7. (**Bonus:** 5 points) Show that the transformation $T: \mathbb{R}^2 \to \mathbb{R}^3$ defined by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} 2x_1 - 3x_2 \\ x_1 + 4 \\ 5x_2 \end{bmatrix}$$

is not linear. (Hint: Consider e_1, e_2 and $e_1 + e_2$.)

8. (**Bonus:** 5 points) Let $T: \mathbb{R}^n \to \mathbb{R}^n$ be a linear transformation. Justify why $T(\mathbf{x}) = \mathbf{A}\mathbf{x}$ for all \mathbf{x} in \mathbb{R}^n if $A = \begin{bmatrix} T(\mathbf{e_1}) & T(\mathbf{e_2}) & \cdots & T(\mathbf{e_n}) \end{bmatrix}$