

1. (15 points) (a) (5 points) Let $A = \begin{bmatrix} -2 & -7 & -9 \\ 2 & 5 & 6 \\ 2 & 6 & 8 \end{bmatrix}$. Calculate the determinant of A .

$$\det A = \begin{vmatrix} -2 & -7 & -9 \\ 2 & 5 & 6 \\ 2 & 6 & 8 \end{vmatrix}$$

$$= \begin{vmatrix} -2 & -7 & -9 \\ 0 & -2 & -3 \\ 0 & -1 & -1 \end{vmatrix} = - \begin{vmatrix} -2 & -7 & -9 \\ 0 & -1 & -1 \\ 0 & -2 & -3 \end{vmatrix} = - \begin{vmatrix} -2 & -7 & -9 \\ 0 & -1 & -1 \\ 0 & 0 & -1 \end{vmatrix}$$

$$= -2 \begin{vmatrix} -2 & -3 \\ -1 & -1 \end{vmatrix} = -2(-1) = \boxed{2} \quad = (-1)(-2)(-1)(-1)$$

(b) (5 points) Let $B = \begin{bmatrix} -2 & 0 & -7 & -9 \\ 7 & 3 & 6 & -1 \\ 2 & 0 & 5 & 6 \\ 2 & 0 & 6 & 8 \end{bmatrix}$. Calculate the determinant of B using a cofactor expansion.

$$\det B = \begin{vmatrix} -2 & 0 & -7 & -9 \\ 7 & 3 & 6 & -1 \\ 2 & 0 & 5 & 6 \\ 2 & 0 & 6 & 8 \end{vmatrix} = 3 \begin{vmatrix} -2 & -7 & -9 \\ 2 & 5 & 6 \\ 2 & 6 & 8 \end{vmatrix} = 3(\det A) = 3 \cdot 2 = \boxed{6}$$

(c) (2 points) Using the properties of the determinant, calculate $\det 2A$.

$$\det 2A = 2^3 \cdot \det A = 2^3 \cdot 2 = \boxed{16}$$

(d) (2 points) Using the properties of the determinant, calculate $\det B^3$.

$$\det B^3 = (\det B)^3 = 6^3 = \boxed{216}$$

(e) (1 point) Is B invertible? Justify your answer.

$$\text{Yes. } \det B = 6 \neq 0.$$

2. (20 points) Consider \mathbb{P}_2 the vector space of all polynomials of degree at most 2.

(a) (5 points) Show that the set of polynomials $\{1+t^2, t-3t^2, 1+t-3t^2\}$ is linearly independent.

$S = \{1, t, t^2\}$ is the standard basis of \mathbb{P}_2 .

$$\begin{aligned} & \left[[1+t^2]_S \quad [t-3t^2]_S \quad [1+t-3t^2]_S \right] \\ &= \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & -3 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & -3 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & -1 \end{bmatrix} \end{aligned}$$

→ has 3 pivots,
by I.M.T.
has linearly independent
columns.

These polynomials have linearly independent coordinate vectors and thus must be linearly independent.

(b) (5 points) Let U be the collection of all polynomials of the form $p(t) = a + t^2$ for any a in \mathbb{R} . Is U a subspace of \mathbb{P}_2 ? If so, show U shows the three properties of a subspace. If not, show one of these properties fail.

No. $p(t) = a + t^2$ and $q(t) = b + t^2$ are in U

but $(p+q)(t) = (a+b) + 2t^2$ is not in U .

(c) (5 points) Define a transformation $T: \mathbb{P}_2 \rightarrow \mathbb{R}^2$ by $T(p) = \begin{bmatrix} p(1) \\ p(0) \end{bmatrix}$. Show that T is linear. (That is, for any polynomials p, q and scalars c we have $T(p+q) = T(p) + T(q)$ and $T(cp) = cT(p)$.)

$$\text{Let } p(t) = a_0 + a_1 t + a_2 t^2, \quad q(t) = b_0 + b_1 t + b_2 t^2$$

$$\text{so } (p+q)(t) = (a_0 + b_0) + (a_1 + b_1)t + (a_2 + b_2)t^2 \quad \text{and}$$

$$(cp)(t) = ~~c a_0 + c a_1 t + c a_2 t^2~~ \quad c a_0 + c a_1 t + c a_2 t^2$$

$$\text{Note } p(0) = a_0, \quad p(1) = a_0 + a_1 + a_2, \quad q(0) = b_0, \quad q(1) = b_0 + b_1 + b_2$$

$$(p+q)(0) = a_0 + b_0, \quad (p+q)(1) = a_0 + b_0 + a_1 + b_1 + a_2 + b_2$$

$$\text{and } (cp)(0) = c a_0, \quad (cp)(1) = c a_0 + c a_1 + c a_2.$$

$$\text{Thus: } T(p+q) = \begin{bmatrix} a_0 + b_0 + a_1 + b_1 + a_2 + b_2 \\ a_0 + b_0 \end{bmatrix} = \begin{bmatrix} a_0 + a_1 + a_2 \\ a_0 \end{bmatrix} + \begin{bmatrix} b_0 + b_1 + b_2 \\ b_0 \end{bmatrix} = T(p) + T(q)$$

$$T(cp) = \begin{bmatrix} c a_0 + c a_1 + c a_2 \\ c a_0 \end{bmatrix} = c \begin{bmatrix} a_0 + a_1 + a_2 \\ a_0 \end{bmatrix} = c T(p). \quad \checkmark$$

(d) (5 points) Give an explicit description of the range and kernel of T via spanning sets. (Hint: Both require at least two linearly independent vectors.)

$$\text{If } p(t) = a + bt + ct^2 \quad \text{then } T(p) = \begin{bmatrix} p(1) \\ p(0) \end{bmatrix} = \begin{bmatrix} a + b + c \\ a \end{bmatrix}.$$

$$\text{So an element of the range is } a \begin{bmatrix} 1 \\ 1 \end{bmatrix} + b \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\text{for some } a, b, c: \quad \boxed{\text{Range}(T) = \text{Span} \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\} = \mathbb{R}^2.}$$

An element of the kernel is a polynomial s.t.

$$T(p) = \begin{bmatrix} a + b + c \\ a \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{aligned} a &= 0 \\ b + c &= 0 \Rightarrow -b = c. \end{aligned}$$

So $p(t)$ is in the kernel if it is of the form

$$0 + bt + (b)t^2 = bt - bt^2 = b(t - t^2).$$

$$\text{So } \boxed{\text{kernel}(T) = \text{Span} \left\{ t - t^2 \right\}}$$

3. (15 points) The following matrices are row equivalent:

$$A = \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 & 9 & 0 \\ 0 & 1 & -5 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

(a) (5 points) For what k is $\text{Col}(A)$ a subspace of \mathbb{R}^k ? For what k is $\text{Nul}(A)$ a subspace of \mathbb{R}^k ?

A is 3×4 so

$\text{Col}(A)$ is in \mathbb{R}^3 , $\text{Nul}(A)$ is in \mathbb{R}^4

(b) (5 points) Find a basis for $\text{Col}(A)$.

$$\left\{ \begin{bmatrix} 2 \\ -2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ -5 \\ 7 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 6 \end{bmatrix} \right\}$$

Use the pivot columns of A

(c) (5 points) Find a basis for $\text{Nul}(A)$. $A\vec{x} = \vec{0}$ if

$$\vec{x} = \begin{bmatrix} -9x_3 \\ -5x_3 \\ x_3 \\ 0 \end{bmatrix} = x_3 \begin{bmatrix} -9 \\ -5 \\ 1 \\ 0 \end{bmatrix}$$

So $\left\{ \begin{bmatrix} -9 \\ -5 \\ 1 \\ 0 \end{bmatrix} \right\}$ is a basis.

4. (20 points) (a) (5 points) Let $A = \begin{bmatrix} 5 & 2 \\ 7 & 1 \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$. Solve the equation $A\mathbf{x} = \mathbf{b}$ using Cramer's rule. No credit will be given for other methods of solution.

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \text{ where } x_1 = \frac{\det(A_1(\vec{b}))}{\det(A)} = \frac{\begin{vmatrix} 3 & 2 \\ 1 & 1 \end{vmatrix}}{\begin{vmatrix} 5 & 2 \\ 7 & 1 \end{vmatrix}} = \frac{1}{-9}$$

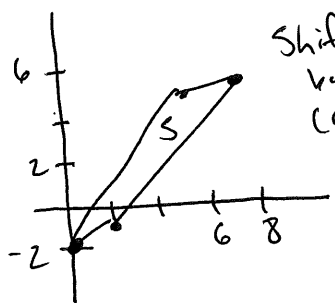
$$x_2 = \frac{\det(A_2(\vec{b}))}{\det(A)} = \frac{\begin{vmatrix} 5 & 3 \\ 7 & 1 \end{vmatrix}}{\begin{vmatrix} 5 & 2 \\ 7 & 1 \end{vmatrix}} = \frac{-16}{-9}$$

- (b) (5 points) Observe that $B = \left\{ \begin{bmatrix} 5 \\ 7 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right\}$ is a basis for \mathbb{R}^2 . Give the coordinate vector for $\mathbf{b} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$ from above relative to B .

From part (a); $A = PB$ so

$$[\vec{x}]_B = \begin{bmatrix} -1/9 \\ 16/9 \end{bmatrix}$$

- (c) (5 points) Compute the area of the parallelogram S with vertices $(0, -2), (5, 5), (2, -1), (7, 6)$.



Shift up by $(0, 2)$

$$\text{Area of } S = \left| \det \begin{bmatrix} 5 & 2 \\ 7 & 1 \end{bmatrix} \right| = |-9| = 9$$

- (d) (5 points) Suppose $C = \{c_1, c_2\}$ is another basis of \mathbb{R}^2 with change of coordinate matrix P_C . Is P_C invertible? Justify your answer.

Yes. $P_C = [\vec{c}_1, \vec{c}_2]$ has linearly independent columns because C is a basis.

By the I.M.T., P_B must be invertible.

5. (15 points) Let $D_{2 \times 2}$ be the collection of all 2×2 diagonal matrices. That is

$$D_{2 \times 2} = \left\{ \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} : a, b \text{ in } \mathbb{R} \right\}.$$

With addition and scalar multiplication defined in the usual way for 2×2 matrices, show that $D_{2 \times 2}$ verifies axioms 2 and 4 of the vector space axioms and is a subspace of $M_{2 \times 2}$.

(a) (5 points) Axiom 2: for all vectors \mathbf{u}, \mathbf{v} , we have $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$.

Let $\vec{u} = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$, $\vec{v} = \begin{bmatrix} c & 0 \\ 0 & d \end{bmatrix}$ be arbitrary elements of $D_{2 \times 2}$.

$$\begin{aligned} \vec{u} + \vec{v} &= \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} + \begin{bmatrix} c & 0 \\ 0 & d \end{bmatrix} = \begin{bmatrix} a+c & 0 \\ 0 & b+d \end{bmatrix} = \begin{bmatrix} c+a & 0 \\ 0 & d+b \end{bmatrix} \\ &= \begin{bmatrix} c & 0 \\ 0 & d \end{bmatrix} + \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} = \vec{v} + \vec{u}. \quad \checkmark \end{aligned}$$

(b) (5 points) Axiom 4: there is a zero vector $\mathbf{0}$ in V such that for any vector \mathbf{u} , we have $\mathbf{u} + \mathbf{0} = \mathbf{u}$.

With \vec{u} as above, if $\vec{0} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ then

$$\begin{aligned} \vec{u} + \vec{0} &= \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} a+0 & 0 \\ 0 & b+0 \end{bmatrix} = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} = \vec{u} \\ &\text{as desired.} \quad \checkmark \end{aligned}$$

(c) (5 points) Verify that $D_{2 \times 2}$ is a subspace of $M_{2 \times 2}$.

Note as $\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ we have

$$D_{2 \times 2} = \text{Span} \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

6. (15 points) Indicate whether each statement is true or false by circling **True** or **False** appropriately.

(a) (3 points) If A and B are $n \times n$ matrices then $\det(AB) = \det(BA)$.

True False

(b) (3 points) If f is a function in the vector space V of all real-valued functions on \mathbb{R} and $f(t) = 0$ for some t , then f is the zero vector in V .

True False

(c) (3 points) The kernel of a linear transformation is not a vector space.

True False

(d) (3 points) If $H = \text{Span}\{\mathbf{b}_1, \dots, \mathbf{b}_p\}$, then $\{\mathbf{b}_1, \dots, \mathbf{b}_p\}$ is a basis for H .

True False

(e) (3 points) Suppose \mathcal{B} is a basis for \mathbb{R}^n and let $P_{\mathcal{B}}$ be the change of coordinate matrix for \mathcal{B} . Then $[\mathbf{x}]_{\mathcal{B}} = P_{\mathcal{B}}\mathbf{x}$ for all \mathbf{x} in \mathbb{R}^n .

True False

7. (Bonus: 5 points) Assume A is an $n \times n$ invertible matrix. Prove that $\det(A^{-1}) = (\det(A))^{-1}$.

(Note: By $(\det(A))^{-1}$, we mean $\frac{1}{\det(A)}$.)

Notice as I_n is diagonal, $\det(I_n) = 1$.

$$\text{So } 1 = \det(I_n) = \det(AA^{-1}) = \det(A) \det(A^{-1})$$

$$\text{which implies } \frac{1}{\det(A)} = \det(A^{-1}).$$

8. (Bonus: 5 points) Recall that a scalar λ is an *eigenvalue* of an $n \times n$ matrix A if

$$Ax = \lambda x$$

has a nontrivial solution. Suppose that a specific matrix A has $\lambda = 0$ as an eigenvalue. Is A invertible or not? Justify your answer.

No. If $\lambda = 0$ is an eigenvalue of A then

$$A\vec{x} = 0\vec{x} = \vec{0}$$

has a nontrivial solution. By the I.M.T.

A must not be invertible.